

Designing the circuitry of a power supply that uses a low-current battery to charge a high-current load requires a good understanding of how different factors can contribute to voltage drop. A 2.5-4.5 V battery is used to charge a 6.3 V load. The battery voltage is measured across the load and compared to the desired output voltage. If the output voltage is lower than the battery voltage, the UCC3954 will increase the current through the MOSFET until the output voltage reaches the desired level. If the output voltage is higher than the battery voltage, the UCC3954 will decrease the current through the MOSFET until the output voltage reaches the desired level. This results in a typical efficiency improvement of 7% at currents of a few hundred millamps. The low-resistance beads are available in small surface-mount packages. Diode Q1 provides a current path at the beginning of the rectifier conduction cycle, because the bead also delays the current through Q1 at turn-on.

**2. Adding a ferrite bead (L2) allows the rectifier to turn off by momentarily blocking the current through the MOSFET when it tries to change direction. This action eliminates the large reverse-current spike, so a typical efficiency gain of 7% over the nonsynchronous design is achieved.**

the current through the MOSFET when it tries to change direction, allowing the rectifier to be properly commutated. This results in a typical

efficiency improvement of 7% at currents of a few hundred millamps. The low-resistance beads are available in small surface-mount packages. Diode

D1 provides a current path at the beginning of the rectifier conduction cycle, because the bead also delays the current through Q1 at turn-on.

**Circle 521**

## Active Cancellation Of A Pot's Wiper Resistance

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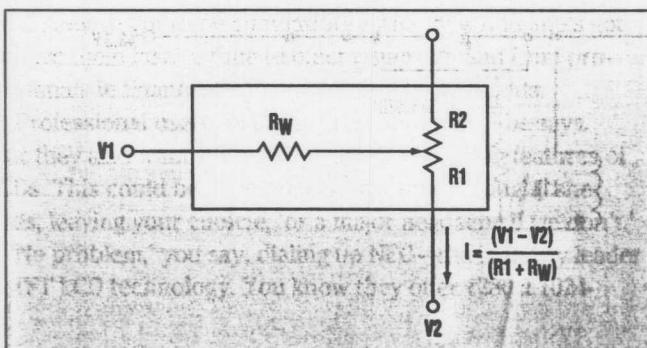
**A**lthough we almost always call them "potentiometers," many (if not most) adjustable resistance devices actually end up being used as two-terminal variable resistors

(rheostats). In actuality, the term "potentiometer" means a three-terminal variable voltage divider.

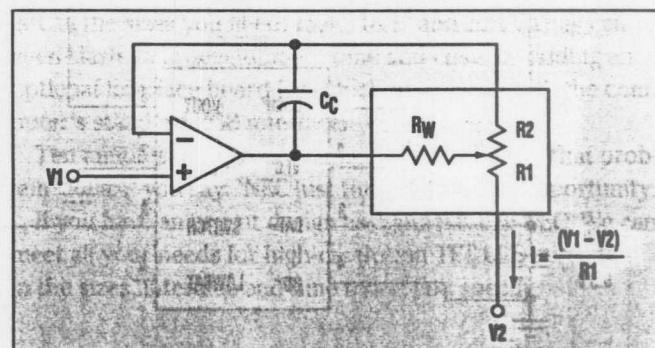
Unfortunately, when used as variable resistors, pots (whether electro-

mechanical or electronic) suffer from a number of non-idealities that can thoroughly bust an error budget. Chief culprits among these parasitics is the "wiper resistance."

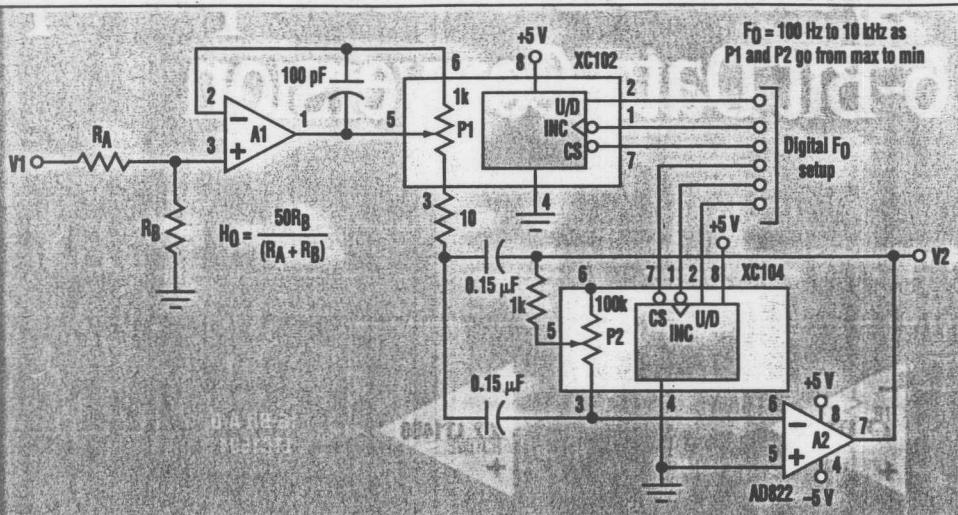
Wiper resistance arises in electro-mechanical pots because they consist of a stationary resistance element over which a sliding contact (wiper) moves to set the desired resistance. Perversely, the contact point between wiper and resistance element itself inevitably makes an undesired non-zero contribution ( $R_w$  in figure 1) to the total resistance ( $R_1 + R_w$ ). The effective resistance of the pot can therefore never be adjusted all the way to zero



**1. Uncompensated wiper resistance ( $R_w$ ) can cause serious instabilities due to time, temperature, and life-cycle wearout mechanisms.**



**2. This arrangement effectively blots out wiper-resistance-related difficulties using electromechanical or electronic potentiometers.**



3. The new topology is put to good use in a wide-range ( $f_0 = 100 \text{ Hz to } 10 \text{ kHz}$ ) Q-of-5, digitally tunable bandpass filter application. DCP P2 does not need this trick due to its larger 2500:1  $R_W$ -to-element ratio.

but instead has a minimum value directly related to  $R_W$ . What's worse,  $R_W$  is strongly influenced by surface phenomena lurking in the mechanical interface between wiper and resistance element. This makes it seriously unstable against time, temperature, and life-cycle wearout mechanisms.

Electronic (digitally controlled) potentiometers (DCPs), on the other hand, escape the contact resistance problems of the mechanical pot. However, they must contend instead with the relatively large  $R_{ON}$  resistances (usually tens of ohms) of the FET switches that implement the multiplexer, which substitutes for the mechanical pot's wiper.

While FETs don't wear out and get noisy like mechanical wipers, the FETs'  $R_{ON}$  temperature coefficients approach 3000 ppm/ $^{\circ}\text{C}$ —five to ten

times worse than typical resistance elements. Therefore, even relatively small  $R_W$  contributions to total circuit resistance may significantly degrade circuit stability. Take, for example, the Xicor XC102 digitally controlled pot. Its 1k resistance element has a tempco of  $\pm 600 \text{ ppm}/^{\circ}\text{C}$  max, and the setting resolution is  $10 \Omega$ .  $R_W$  is typically  $40 \Omega$ . For resistance settings of  $200 \Omega$  or less, the overall resistance tempco is dominated by  $R_W$ . In addition, because  $R_W$  can range as high as  $100 \Omega$ , the resistance setting accuracy is at the mercy of  $R_W$  for settings below  $500 \Omega$ . Not a pretty picture.

Figure 2 illustrates a way to effectively blot out these  $R_W$ -related difficulties. It relies on the fact that, since the resistance component  $R_2$  conducts only negligible (op amp bias) currents, the voltage at the amplifiers (-) input

is essentially the same as the voltage at the  $R_1-R_2$  node and therefore equal to  $(I * R_1 + V_2)$  independent of  $R_W$ . Consequently, when the op amp forces the  $R_1-R_2$  node to  $V_1$  (as it must to maintain input balance),  $I$  is forced to accurately equal  $(V_1 - V_2)/R_1$ , and thus the  $R_W$  effects vanish. Optional frequency compensation in the form of  $C_C$  will sometimes be needed to avoid op-amp feedback instability resulting from phase shift in  $R_2$ .

Figure 3 shows the new topology put to good use in a wide-range ( $f_0 = 100 \text{ Hz to } 10 \text{ kHz}$ ) Q-of-5, digitally tunable bandpass filter. DCP P2 (100k) isn't bothered much by  $R_W$  effects, due to

its typical 2500:1  $R_W$ -to-element resistance ratio. Therefore, it wouldn't benefit from Figure 2's trickery. But DCP P1's performance would be compromised significantly (due to its 25:1 ratio) at low-resistance (high-frequency) settings if nothing were done to cancel its  $R_W$ . A1 does that while simultaneously buffering the  $R_A-R_B$  voltage divider, the adjustment of which can set passband gain anywhere from 0 to 50.

The incremental (up/down) digital interface of P1 and P2 makes this filter ideal for frequency-tracking applications. Such applications have a phase-sensitive quadrature detector/comparator combination that can be used to generate the up/down direction control signal for both DCPs. As a result, it's possible to implement a feedback loop that will automatically converge on optimum tuning.

### Circle 522

## Better Linearity For Frequency-To-Voltage Converters

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In many applications, such as frequency-locked-loop circuits or tachometers, a dc voltage proportional to an input frequency is required. Some special ICs are specifically designed for a highly linear frequency-to-

voltage conversion (e.g., the AD650 from Analog Devices). However, these devices aren't commonly available, compared to simple CMOS 4000 series or 74HC series ICs, and their price is typically much higher. On the other hand, if an inexpensive one-shot such as a 74HC423 or a CD4528 is used for frequency-to-voltage conversion, the linearity is generally unsatisfactory.

Adding a very simple RC network improves the linearity between dc output voltage  $U_{DC}$  and input frequency  $f$  by least one decade. The figure illustrates a standard frequency-to-voltage conversion arrangement